

AACD models – Summary

Notations

- $x_i = t_i - t_{i-1}$ where t_i : arrival time of event i . x_i is called the duration.
- I_i denotes all information available at time t_i

Model

- $x_i = g(\psi_i)\varepsilon_i$ where ε_i is the standardized duration. $\{\varepsilon_i\}$ are identically distributed with pdf f such that f has a strictly positive support and $E\varepsilon_i = 1$.
- $\psi_i = E(x_i|I_{i-1})$ is the conditional duration. One assumption of the model is that ψ_i and ε_i are independent.
- The evolution equation of ψ_i is given by

$$f_\lambda(\psi_i) = \frac{\psi_i^\lambda - 1}{\lambda} = \omega_* + \sum_{l=1}^r \alpha_l^* \psi_{i-l}^\lambda \text{Shock}(\varepsilon_{i-l}) + \sum_{k=1}^q \beta_k \left(\frac{\psi_{i-k}^\lambda - 1}{\lambda} \right),$$

i.e.

$$\psi_i^\lambda = \omega + \sum_{l=1}^r \alpha_l \psi_{i-l}^\lambda \text{Shock}(\varepsilon_{i-l}) + \sum_{k=1}^q \beta_k \psi_{i-k}^\lambda$$

where $\text{Shock}(\varepsilon) = [|\varepsilon - b| - c(\varepsilon - b)]^\nu$, and $\omega = \lambda\omega_* - \sum_{k=1}^q \beta_k + 1$ and for $l = 1..r$, $\alpha_l = \lambda\alpha_l^*$. b is called the shift parameter and c is the rotation parameter. ν is a shape parameter that controls the convexity of the shock impact curve. λ is the Box-Cox parameter. It defines the Box-Cox transformation done on the conditional duration.

- $g(\psi_i)$ depends only on the distribution of ε_i , i.e. on f
 - $f \equiv \text{Exponential}(1)$: $g(\psi_i) = \psi_i$
 - $f \equiv \text{Weibull}(1, \gamma)$: $g(\psi_i) = \psi_i \cdot \frac{1}{\Gamma(1+\frac{1}{\gamma})}$
 - $f \equiv \text{Generalized Gamma}(1, \gamma, \kappa)$: $g(\psi_i) = \psi_i \cdot \frac{\Gamma(\kappa)}{\Gamma(\kappa+\frac{1}{\gamma})}$
 - $f \equiv \text{Burr}(\mu, \kappa, \sigma^2)$ under the constraint $\mu = 1$: $g(\psi_i) = \psi_i \cdot \frac{(\sigma^2)^{1+\frac{1}{\kappa}} \Gamma(\frac{1}{\sigma^2+1})}{\Gamma(1+\frac{1}{\kappa}) \cdot \Gamma(\frac{1}{\sigma^2-\frac{1}{\kappa}})}$